Discretely Following a Curve

Tim Wylie¹

Department of Computer Science, The University of Alberta, Edmonton, AB, Canada T6G-2E8. Email: twylie@cs.ualberta.ca.

Abstract. Finding the similarity between paths is an important problem that comes up in many areas such as 3D modeling, GIS applications, ordering, and reachability. Given a set of points S, a polygonal curve P, and an $\varepsilon > 0$, the discrete set-chain matching problem is to find another polygonal curve Q such that the nodes of Q are points in S and $d_F(P,Q) \le \varepsilon$. Here, d_F is the discrete Fréchet distance between the two polygonal curves. For the first time we study the set-chain matching problem based on the discrete Fréchet distance rather than the continuous Fréchet distance. We further extend the problem based on unique or non-unique nodes and on limiting the number of points used. We prove that three of the variations of the set-chain matching problem are **NP**-complete. For the version of the problem that we prove is polynomial, we give the optimal substructure and the recurrence for a dynamic programming solution.

1 Introduction

Matching geometric objects and finding paths through designated points are common problems in many areas of research such as pattern matching, computer vision, map routing, protein structure alignment, ordering, etc. Some of these path problems are fundamental, and are used to define complexity classes and completeness. A problem closely related to our study here is map matching where the goal is to find a path through an embedded graph that minimizes the distance from a given polygonal curve [4]. This has several useful applications, as mentioned by Alt et al., such as determining the path of a vehicle on a road network (graph) given noisy approximate GPS data (polygonal curve). For map matching, the distance measure used is the Fréchet distance.

The Fréchet distance was originally defined by Maurice Fréchet in 1906 as a measure of similarity between two parametric curves [9]. In the early 1990s, the Fréchet distance between polygonal curves was studied by Alt and Godau [5] who presented efficient algorithms and time bounds of $O(mn \log mn)$, where m, n are the number of vertices in the polygonal curves. Following in 1994 Eiter and Mannila [7] defined the discrete Fréchet distance as an approximate solution to the Fréchet distance based on polygonal curves where only the nodes are taken into consideration.

With the continuous Fréchet distance, the time complexity of map matching on a complete graph was further improved upon in [12] where a new problem was introduced-which we will call set-chain matching (it was unnamed in this work). Given a polygonal curve P, a set of points S, and a maximum distance $\varepsilon > 0$, the problem is to find another polygonal curve, Q, through the set of points such that the Fréchet distance between the new curve and the original are within an allowed distance, $d_F(P, Q) \leq \varepsilon$.



Figure 1. An instance of the set-chain matching problem in 2D with one solution of $k \ge 11$.

Beyond the original work, we investigate many variations. We look at the complexity of set-chain matching based on the discrete Fréchet distance, and although the original definition allowed points in the set to be reused in the path, we now consider both unique and non-unique points. We show that the unique point versions are **NP**complete, and the non-unique point versions are **NP**-complete when restricting the size of the set of points used, but polynomial when limiting the size of the path. Figure 1 shows a simple instance of the set-chain matching problem, which is formally defined at the beginning of Section 3.

The variations of discrete set-chain matching have many applications. Suppose we have intermittent lossy GPS vehicle data where we can not guarantee the path of the vehicle between our data points. We can find the shortest (and arguably the most plausible) path of the vehicle based on the discrete Fréchet distance. If the points in our set represent signal towers (cellular, radio, etc.), which generally have a spherical range, then we can also consider several coverage problems. Assuming we know the path of a vehicle, what is the minimum number of towers needed to ensure that the signal is not lost. Simply knowing whether the path is covered is important, but optimizing it along multiple roads and areas is crucial. These types of problems are studied in many areas related to wireless sensor networks, graphics, scheduling, and ordering.

We first provide some background and related work in Section 2. We then cover the definitions and variations of the discrete set-chain matching problem in Section 3. Sections 4, 5, and 6 follow with the actual results of the problems. Finally, we conclude in Section 7 and give some future work related to this research.

2 Background

With respect to map matching, the problem of finding a path in a graph given a polygonal line was first posed by Alt et al. [4] as follows: Let G = (V, E) be an undirected connected planar graph with a given straight-line embedding in \mathbb{R}^2 and a polygonal line P, find a path π in G which minimizes the Fréchet distance between P and π . They give an efficient algorithm which runs in $O(pq \log q)$ time and O(pq) space where pis the number of line segments of P and q is the complexity of G, but it also allowed vertices and edges to be visited multiple times.

The recent work by Maheshwari et al. improved the running time for the case of a complete graph [12]. The original algorithm decides the map matching problem in

 $O(pk^2 \log k)$ where k is the number of vertices in the graph, and the new algorithm solves it in $O(pk^2)$. Although they do not specify the name for the problem, we refer to it as set-chain matching to avoid confusion with other matching problems. Formally, the set-chain matching problem is defined as: Given a point set S and a polygonal curve P in \mathbb{R}^d ($d \ge 2$), find a polygonal curve Q with its vertices chosen from S, which has a minimum Fréchet distance to P. They decide this problem in $O(pk^2)$, and also give an algorithm to find the minimal Fréchet distance in $O(pk^2 \log pk)$.

We originally noted the complexity of discrete set-chain matching with unique nodes, without the actual proof, in [18]. We not only prove it here, but we also show that the continuous version of the problem with unique points is **NP**-complete. This is a straightforward extension of our earlier work, but the result was simultaneously and independently proven by Accisano and Üngür [1] and Shahbaz [15].

A variation of the discrete set-chain matching problem is also related to the discrete unit disk cover (DUDC) problem when limiting the number of points from S used. The DUDC problem is known to be **NP**-Hard, and is also difficult to approximate with the most recent results being an 18-approximation algorithm [6], a 15-approximation algorithm [8], and a $(9 + \varepsilon)$ -approximation algorithm [2]. Nearly all of the constant factor approximations have been within the last decade. The problem does admit a PTAS [14], but this is infeasible for most instances of the problem. DUDC does not admit a Fully Polynomial Time Approximation Scheme (FPTAS) unless **P=NP**.

The discrete Fréchet distance was originally defined by Eiter and Mannila [7] in 1994, and was further expanded on theoretically by Mosig et. al. in 2005 [13]. Given two polygonal curves, we define the discrete Fréchet distance as follows. We use d(a, b) to represent the euclidean distance between two points a and b, but it could be replaced with other distance measures depending on the application.

Definition 1. The discrete Fréchet distance d_F between two polygonal curves $f : [0, m] \rightarrow \mathbb{R}^k$ and $g : [0, n] \rightarrow \mathbb{R}^k$ is defined as:

$$d_F(f,g) = \min_{\sigma:[1:m+n] \to [0:m], \beta:[1:m+n] \to [0:n]} \max_{s \in [1:m+n]} \left\{ d\Big(f(\sigma(s)), \, g(\beta(s))\Big) \right\}$$

where σ and β range over all discrete non-decreasing onto mappings of the form σ : $[1:m+n] \rightarrow [0:m], \beta: [1:m+n] \rightarrow [0:n].$

The continuous Fréchet distance is typically explained as the relationship between a person and a dog connected by a leash walking along the two curves and trying to keep the leash as short as possible. However, for the discrete case, we only consider the nodes of these curves, and thus the man and dog must "hop" along the nodes of the curves. Consider the scenario in which a person walks along A and a dog along B. Intuitively, the definition of the paired walk is based on three cases:

- 1. $|B_i| > |A_i| = 1$: the person stays and the dog hops forward;
- 2. $|A_i| > |B_i| = 1$: the person hops forward and the dog stays;
- 3. $|A_i| = |B_i| = 1$: both the person and the dog hop forward.

By giving a dynamic programming solution for finding the discrete Fréchet distance between two polygonal curves, Eiter and Mannila proved:

Theorem 1. The discrete Fréchet distance between two polygonal curves, with m and n vertices respectively, can be computed in O(mn) time [7].

Figure 2 shows the relationship between the discrete and continuous Fréchet distances. In Figure 2(a), we have two polygonal curves (or chains) $\langle a_1, a_2, a_3 \rangle$ and $\langle b_1, b_2 \rangle$, the continuous Fréchet distance between the two is the distance from a_2 to segment $\overline{b_1 b_2}$, i.e., $d(a_2, o)$. The discrete Fréchet distance is $d(a_2, b_2)$. The discrete Fréchet distance could be quite larger than the continuous distance. On the other hand, with enough sample points on the two curves, the resulting discrete Fréchet distance, i.e., $d(a_2, b)$ in Figure 2(b), closely approximates $d(a_2, o)$.



Figure 2. The relationship between the discrete and continuous Fréchet distance where *o* is the continuous and the dotted line between nodes is the discrete. (a) shows a case where the curves have fewer nodes and a larger discrete Fréchet distance, while (b) is the same basic path with more nodes, and thus provides a better approximation of the Fréchet distance.

3 Discrete Set-Chain Matching

We begin with the formal definitions of the problem and the variations as well as some terminology. It is important to note that, as in the continuous version, we make no requirements that P or Q be planar. For discussion, we will refer to the number of nodes in a polygonal curve as the "size" of the curve and it will be denoted as |A| for a polygonal curve A.

Definition 2 (The Discrete Set-Chain Matching Problem).

Instance: Given a point set S, a polygonal curve P in \mathbb{R}^d $(d \ge 2)$, an integer $K \in \mathbb{Z}^+$, and an $\varepsilon > 0$.

Problem: Does there exist a polygonal curve Q with vertices chosen from S' where $S' \subseteq S$, such that $T \leq K$ and $d_F(P,Q) \leq \varepsilon$?

T is defined in two ways. When limiting the number of nodes in the curve, T = |Q|, and if restricting the number of points used then T = |S'|. Figure 3 shows an example demonstrating the difference between minimizing |Q| or |S'|. Here, minimizing |Q| will always yield |Q| = 3 regardless of the points chosen. However, minimizing |S'| will return |S'| = 2 and |Q| = 3, which is the only set of points that is minimal.

We look at three variations of discrete set-chain matching. They vary whether there is a uniqueness constraint on $s \in S$ being used as a node in Q (if points may be used more than once), and whether our goal is to limit the size of the curve Q or the set S'. We distinguish the problems as Unique/Non-unique(U/N) Set-Chain(S) Matching(M)



Figure 3. The difference between minimizing |Q| and |S'|. Minimizing |S'| gives $Q = \langle s_1, s_2, s_1 \rangle$ where |S'| = 2 and |Q| = 3, but minimizing |Q| will yield |Q| = 3 whether it uses the sequence $\langle s_1, s_2, s_1 \rangle$ or $\langle s_1, s_2, s_3 \rangle$.

with a k Subset/Curve(S/C). The variants are thus NSMS-k, NSMC-k, and USM-k. When looking at unique nodes, limiting |Q| is equivalent to limiting the set of points used, |S'|, since they can only be used once, so we do not separate the cases.

4 Set-Chain Matching with T = |Q| (NSMC-*k*)

The original set-chain matching work dealt with the continuous version of NSMC-k. The discrete version is decidable with a straightforward dynamic programming solution. We first overview the recurrence relation and algorithm to solve the optimization version, and show that that NSMC-k exhibits an optimal substructure.

Figure 3 demonstrates that we must find at least one point $s_i \in S$ for every $p_j \in P$. The recurrence relation is shown in Equation 1. It assumes a 2D array, M, of size $|S| \times |P|$ where the columns represent the nodes in the polygonal curve P and the rows represent points in the set S. The initial condition assumes a column zero populated with 0's in every row. The recurrence can then be processed column by column until finished. The final optimal value will be $Opt = \min_{k=1}^{|S|} (M[k, |P|])$. This can be solved in O(mn) time. A straightforward iterative algorithm that implements this method and solves the optimization version of the problem is easy to construct. The optimal result is then used to decide NSMC-k.

$$M[i,j] = \min \begin{cases} M[i,j-1], & \text{if } d(s_i,p_j) \le \varepsilon, M[i,j-1] \ne \emptyset\\ \min_{k=1}^{|S|} (M[k,j-1]) + 1, & \text{if } d(s_i,p_j) \le \varepsilon, M[i,j-1] = \emptyset \\ \emptyset, & \text{if } d(s_i,p_j) > \varepsilon \end{cases}$$
(1)

Theorem 2 (Optimal Substructure of NSMC-*k*). Let $P = \langle p_1, ..., p_n \rangle$ be a polygonal chain, and $S = \{s_1, ..., s_m\}$ be a set of points such that there exists a $Q = \langle q_1, ..., q_k \rangle$ through a set $S' \subseteq S$ which is a minimum sequence such that $d_F(P,Q) \leq \varepsilon$. (1) If $d(p_{n-1}, q_k) \leq \varepsilon$ and $d(p_{n-1}, q_{k-1}) > \varepsilon$, then Q_k is an optimal solution for P_{n-1} . (2) If $d(p_{n-1}, q_k) \leq \varepsilon$, then Q_{k-1} is an optimal solution for P_{n-1} . (3) If $d(p_{n-1}, q_k) > \varepsilon$, then Q_{k-1} is an optimal solution for P_{n-1} .

Proof. (1) If $d(p_n, q_k) \leq \varepsilon$ and $d(p_{n-1}, q_k) \leq \varepsilon$, then the point q_k covers both points by an ε -ball. However, q_{k-1} does not cover p_{n-1} . Thus, Q_k is still the optimal solution.

(2) If $d(p_{n-1}, q_{k-1}) \leq \varepsilon$, then q_k only covers p_n . If $d(p_n, q_{k-1}) \leq \varepsilon$, then Q_{k-1} would be an optimal solution, but by definition Q was minimal so this can not be true. (3) If $d(p_{n-1}, q_k) > \varepsilon$, then we have the same argument with p_n only covered by q_k , and thus Q_{k-1} must be optimal for P_{n-1} .

Theorem 3. The discrete non-unique set-chain matching problem where T = |Q| is polynomial, i.e., NSMC- $k \in P$.

Proof. Since we have shown that NSMC-k has an optimal substructure, given P, S, and K, we can find an optimal K' from a dynamic programming algorithm based on the recurrences (Equation 1). Then we decide NSMC-k by comparing whether $K \leq K'$. \Box

5 Set-Chain Matching with T = |S'| (NSMS-k)

The discrete non-unique set-chain matching problem where we limit the number of points from S used as nodes in Q turns the problem into a coverage issue. This problem is equivalent to the discrete unit disk cover (DUDC) problem, which is known to be **NP**-Hard and is difficult to approximate.

Theorem 4. The discrete non-unique set-chain matching (NSMS-k) problem where T = |S'| is **NP**-complete.

Proof. This can be shown via a straightforward reduction from the discrete unit disk cover (DUDC) problem which is **NP**-Hard [6]. Formally, we are given a set of points P and a set of disks $D = \{D_1, D_2, ..., D_N\}$ with centers $C = \{c_1, c_2, ..., c_N\}$ with all disks of radius r.

Now, let P' be a polygonal curve made of all points in P in any order. Let S = Cand $\varepsilon = r$. Now, \exists a minimum-cardinality subset $D' \subseteq D$ with centers C' such that $\forall p \in P, \exists a D_i \in D'$ that contains p if and only if \exists a polygonal curve Q where the vertices are from points in $S' \subseteq S$ such that |S'| = |D'| and $d_F(P', Q) \leq \varepsilon$.

We first prove the forward direction. Given an instance $I \subseteq D$ that is a minimum covering for all points in P. We construct P' by connecting all points in P in any order. Making a polygonal curve Q with the set of centers (C_I) of I is straightforward. We construct Q by finding the disk (D_i) that covers $p_1 \in P'$, and we set $q_1 = c_i$ where c_i is the center of disk D_i . Similarly, we walk through each $p_i \in P'$ and set the center of the disk $D_j \in I$ covering point p_i as $q_i = c_j$. Every ordered node in P' is now still within ε of a node in Q, thus $d_F(P', Q) \leq \varepsilon$, and the set of nodes used, |S'|, is equal to |I|.

In the other direction, if we have a polygonal curve $Q = \{q_1, q_2, \ldots, q_N\}$ such that the number of unique locations used for vertices is of minimum cardinality and $d_F(P',Q) \leq \varepsilon$. Suppose the set of unique locations S' that Q is made of is not a minimal disk cover of all the vertices of P' viewed as points in a set P. This implies there exists at least one q_i that is unnecessary for a covering by C, and there is a point p_j that can be covered by another c_k . Let C' be this smaller covering. Using the same construction as above we can build a P'' and Q'. This would mean |C'| < |S'| which contradicts our assumption that S' in minimal. Thus, every node $p_i \in P'$ is within ε of at least one node $q_j \in Q$, and S' is a minimum cover.

Finally, we show the problem is in NP. Given an instance I we can check whether $d_F(P, I) \leq \varepsilon$ in O(mn) time via Theorem 1.

7

6 Unique Set-Chain Matching (USM-k)

We now address unique set-chain matching where any point from the set can be used at most once, and show that this problem is **NP**-complete via a reduction from planar 3-SAT [11]. Planar 3-SAT is any 3-SAT formula that can be drawn as a planar graph with vertices representing clauses and variables. This is a convenient form of 3-SAT for geometric reductions since a crossover gadget is unnecessary.

By standard convention, we first introduce several planar "gadgets" that we then arrange in our reduction. We will build up the gadgets in a piecewise manner, and then show how they are connected to form a single polygonal curve. Due to the length of this section, we cover the gadgets and then formally do the reduction with the assumption of their correctness.

Let φ be the 3-SAT formula represented by the input instance of planar 3-SAT with N variables and M clauses. Given an $\varepsilon > 0$, we construct a point set S and a polygonal curve P and let $K = |S_{\varepsilon}| = |S|$ requiring all points to be used. Here, $S_{\varepsilon} = \{s \in S | p \in P \text{ and } d(p, s) \le \varepsilon\}$ and referred to as the set of reachable points. We show that φ is satisfiable if and only if with our construction there exists a polygonal curve Q with unique nodes from the set S such that $d_F(P, Q) \le \varepsilon$, i.e. $|Q| = |S| \le K$.

6.1 Choices and Chains

We first look at the main building block for our gadgets in this reduction, which is the choice gadget shown in Figure 4(a). There are two ways for a new curve to be constructed starting at a and using the points $\{a, b, c\}$ in order to "cover" the nodes of the curve $\langle x, y, z \rangle$. We label the curve $\langle a, b, c \rangle$ as **true**, and the curve $\langle a, c, b \rangle$ as **false**. This is because the second curve violates our ε constraint since $d(b, z) > \varepsilon$.



Figure 4. (a) A choice gadget. (b) A chain with a false connection. (c) A variable gadget.

Choice gadgets are linked together to make a chain. Chain gadgets are important because they force a new curve to stay in a **true** or **false** orientation, and therefore transfer information. An example of a chain with a **false** curve is shown in Figure 4(b).

6.2 The Variable Gadget

The base of the variable gadget is shown in Figure 4(c). A **true** setting begins the new chain as $\langle s_1, s_2, s_3, s_6 \rangle$ while a **false** setting begins $\langle s_1, s_3, s_2, s_4, s_5 \rangle$. The different settings change whether s_4 is needed to keep $d_F(P,Q) \leq \varepsilon$. A **true** setting does not need the extra node while the **false** does. This free node is what is propagated to the clause gadget. Figure 5 shows the full variable gadget. As is standard in many reductions, each

variable is repeated some finite length while alternating between x and $\neg x$ based on what is needed in the equation.



Figure 5. Variable gadgets linked together for variable x_i where x_i is set to **false** (s_{i_4} is used) and thus $\neg x_i$ is **true** (s_{i_7} is free).

Unfortunately, the variable gadget alone will not ensure that the new curve alternates between **true** and **false** configurations, which we need for a variable and its complement. Therefore, the variable gadget has a "switch" component, which makes the free point necessary at every other variable gadget, and thus alternates Q between **true** and **false** paths. It is important to note that these switch segments will not be connected to the variable gadgets within ε . Note in Figure 5 that the first and last instance of the variable gadget do not have the full switch component.

For our planar 3-SAT instance, there may be edges which need to connect from the top and the bottom of the variable gadget. Although an example is not given, this is possible with our variable gadget. Looking at Figure 5, imagine everything is rotated in the gadget from s_{i_7} to s_{i_E} around that vector. This flips the variable and half of the switch component without changing the reduction, which allow attaching chains onto the other side of the variable gadget. The following switch component would also have to be below and then flip back up.

6.3 The Clause

A clause gadget is straightforward. As shown in Figure 6(a), three chains meet within ε of each other $(c_{i_1}, c_{i_2}, c_{i_3})$, and there are only two points between them. Each chain is connected at the other end $(v_{i_1}, v_{i_2}, v_{i_3})$ to variable gadgets. The **true** or **false** setting from the variable is propagated up to the clause gadget and at least one of the chains must have the new curve in a **true** position. Only two of the chains can have a **false** setting or else one of the end nodes (C_{k_i}) in the clause gadget will not be within ε of any available point, which is equivalent to the clause being **false** in 3-SAT. Also note that in the clause gadget, if either point is not needed, they can be used by a **true** chain so that all points are used.

The chains from the clause gadgets are attached to the variable gadgets in the highlighted area of Figure 6(b). There is one point between the ends of the three chains. A segment is added from the clause endpoint v_{ky} (for clause c_k where $1 \le y \le 3$) to the



Figure 6. (a) The clause gadget. (b) The connection point between a variable gadget and a chain to the clause gadget.

opposite side of the switch component of the variable (or complement) desired, e.g., if x_1 is the third variable in the clause c_k and the connection point is $n_{1_i}(x_1)$ or $n_{1_j}(\neg x_1)$, then a segment is placed connecting the chain v_{k_3} to $n_{1_i}(\neg x_1)$.

6.4 Connecting the Gadgets

Although the polygonal curve P does not have to be planar, it must be a single continuous curve. Here, we will show that all the gadgets and segments can be connected to form P. The non-planarity allows us to focus on a single clause gadget to show one way in which everything can be connected. We have to be careful that we do not connect two nodes that would change the reduction such as connecting two end nodes at a clause- $c_{k_1}, c_{k_2}, c_{k_3}$ for clause C_k . For simplicity, we can connect all variables together and all the beginning and end switch points. Let $q_1 = p_{1_1}$ and then connect the variable gadgets by adding in the edge $\overline{p_{k_F}p_{k+1_1}}$ for all variables $1 \le k \le N - 1$, and the last variable node p_{N_F} connects to a vertex in C_1 .



Figure 7. Example USM-k clause with three variables $C_k = (\neg x_1 \cup x_2 \cup \neg x_3)$.

We show a simple example of three variables and a clause in Figure 7 without the connecting segments between gadgets. Let this be clause C_k , and the connected variables be x_1, x_2, x_3 , at nodes n_{t_i} or n_{t_j} where $1 \le t \le 3$ and let n_{t_j} be the end

node of the curve beginning with n_{t_i} (this will be either $n_{t_{i-1}}$ or $n_{t_{i+1}}$). We are only concerned about the end nodes of curves connected to the clause gadget. The other chains will be taken care of separately, including those which we will ignore for now (the switch component chains n_{1_3} to n_{1_4} and n_{3_3} to n_{3_4} in our example).

The end nodes of the curves that need to be connected are c_{k_1} , c_{k_2} , c_{k_3} , $n_{1_j}(n_{1_1})$, $n_{2_i}(n_{2_4})$, $n_{3_j}(n_{3_1})$. These can be connected as a single chain, with every edge longer than ε , by creating the segments $\overline{n_{1_j}c_{k_2}}$, $\overline{n_{2_i}n_{3_j}}$, and then c_{k_1} and c_{k_3} are the end nodes of the new curve. If we do this for all clauses, then we can connect the clauses with the segments $\overline{c_{k_3}c_{k+1_1}}$ for $1 \le k \le M - 1$.

The only remaining unconnected curves are the switch components that are not tied to a clause gadget. These can be connected in any order provided the end nodes are not within ε , and we do not introduce a loop. This is straightforward by connecting every other switch component curve (never creating the segments $\overline{n_{t_{i-1}}n_{t_i}}$ or $\overline{n_{t_i}n_{t_{i+1}}}$ for $1 \le t \le N$), and then connecting all the skipped curves.

6.5 The Reduction

Theorem 5. The discrete unique set-chain matching (USM-k) problem is NP-complete.

Proof. We are given a planar 3-SAT instance $G_{\varphi} = \{V, E\}$ with vertices $V = X \cup C$ such that the vertices represent variables $X = \{x_1, x_2, \ldots, x_N\}$ and clauses $C = \{C_1, C_2, \ldots, C_M\}$, and the edges $E = \{e_1, e_2, \ldots, e_Z\}$ connect variables to clauses with the degree of each $C_i \in C$ being three. Given the planar 3-SAT instance G_{φ} , we construct a polygonal curve P and a point set S using an $\varepsilon > 0$ based on the method described. This construction takes O(|C| + |X| + |E|) for constructing P and S and is thus polynomial. The sizes of P and S are dependent on ε and the metric space. In general, for any edge $e_i \in E$ in the space, where $||e_i||$ is the length of the edge, there are $\lceil ||e_i||/\varepsilon \rceil$ points in S and nodes of P used to transfer information along that edge.

We also refer to the 3-SAT equation φ derived from G_{φ} for the satisfiability of G_{φ} . The planar 3-SAT equation φ derived from G_{φ} is satisfiable if and only if there exists a polygonal curve Q with nodes from the set S such that $d_F(P,Q) \leq \varepsilon$ and each point represents a unique node in Q.

In the forward direction, we look at the value of φ . First, we assume φ is satisfiable. For every clause, there is at least one variable which has a **true** value. In our construction this means at least one chain does not need a point from the center of the clause gadget, and thus we can easily find a Q such that $d_F(P, Q) \leq \varepsilon$.

If φ is unsatisfiable, then there is at least one clause where all three variables have a **false** value. This means there is a clause gadget in our construction where all three chains are in a **false** setting, and all need a point in the clause gadget center (Figure 6(a)). However, since there are only two points within ε of the clause gadget chains (the points $c_{i_1}, c_{i_2}, c_{i_3}$ for clause gadget C_i), one chain must use a point outside the clause gadget. This causes $d_F(P, Q) > \varepsilon$.

In the other direction, assume there exists a path Q through $S' \subset S$ such that $d_F(P,Q) \leq \varepsilon$. There must be at least one **true** chain at each clause gadget, and since the three chains propagate this setting from the variable, we know at least one variable (or complement) was **true**. Thus, for every variable attached to a clause, it has the

correct **true** or **false** setting. Therefore, if $d_F(P,Q) \leq \varepsilon$, then the current assignment of each variable also satisfies φ .

If no path Q exists such that $d_F(P, Q) \leq \varepsilon$, then there is at least one clause gadget where all three chains had **false** settings and needed an extra point for Q within the clause gadget. Since the variable gadgets and switch components always have a path within ε , the problem must occur in a clause. Again, this only happens if all three chains have a **false** setting, and similarly to the previous example, these propagated along the chains from the attachments to the variable gadgets. Thus, there must also exist a clause in φ where all three variables are **false**.

Last, we know the problem is in NP. Given an instance I we can check whether $d_F(P, I) \leq \varepsilon$ in O(mn) time via Theorem 1.

Our reduction is based on the discrete Fréchet distance, but our construction also ensures that any resulting path Q is within ε of P along the edges as well. Thus, our reduction can be adapted to prove that USM-k is also **NP**-complete for the continuous Fréchet distance. This result was also recently proven independently and with unique reductions in [1] and [15]. Due to this result being known and for space concerns, we only supply the basic outline of the proof.

Corollary 1. The unique set-chain matching (USM-k) problem based on the continuous Fréchet distance is **NP**-complete.

Proof. This can be proven based on the polygonal curves P and Q being constructed of straight line segments. Given two line segments $a = \langle p_1, p_2 \rangle$ and $b = \langle p'_1, p'_2 \rangle$, it is straightforward to see that if $d(p_1, p'_1) \leq \varepsilon$ and $d(p_2, p'_2) \leq \varepsilon$, then under the continuous Fréchet distance $d_{\mathcal{F}}(a, b) \leq \varepsilon$.

Further, it is known that for any two polygonal curves, $d_{\mathcal{F}}(P,Q) \leq d_F(P,Q)$ [7]. Thus, if both P and Q are polygonal curves and the problem is **NP**-complete for the discrete Fréchet distance within ε , it will also hold for the continuous Fréchet distance within an $\varepsilon' \leq \varepsilon$ and an instance can be verified in $O(mn \log mn)$ [5].

7 Conclusion

In this paper we have outlined and extended the discrete set-chain matching problem and other variations based on restricting our selection to unique nodes, the number of nodes allowed in the curve, or the number of points to choose from. We proved that two variations are **NP**-complete, and the unique point variation is still **NP**-complete when based on the continuous Fréchet distance. We proved that the other variation is polynomial, and gave the recurrences for a dynamic programming implementation. We conclude with some open problems and further research directions for this work.

(1) What are the complexities based on maximizing the number of vertices in Q?

(2) We can also reverse the problem- if we are given a set size for Q, can we minimize the discrete Fréchet distance between P, Q, i.e., $d_F(P, Q) \le \varepsilon$?

(3) What are the complexities with imprecise input? How difficult is it to find the minimum and maximum length Q while respecting the discrete Fréchet distance? This builds off computing the discrete Fréchet distance with imprecise input in general [3].

(4) What are the approximation bounds for the optimization versions? We know NSMS-k is equivalent to DUDC which generally only admits high approximations.

References

- P. Accisano and A. Üngör. Hardness results on curve/point set matching with Fréchet distance. In *Proc. of the 29th European Workshop on Computational Geometry*, EuroCG'13, pages 51–54, Mar 2013.
- 2. R. Acharyya, M. B., and G. K. Das. Unit disk cover problem. CoRR, abs/1209.2951, 2012.
- H.-K. Ahn, C. Knauer, M. Scherfenberg, L. Schlipf, and A. Vigneron. Computing the discrete Fréchet distance with imprecise input. In *Proc. of the 21st Int. Sym. on Algorithms and Computation (ISAAC 2010)*, volume 6507 of *Lecture Notes in Computer Science*, pages 422– 433. Springer-Verlag, 2010.
- H. Alt, A. Efrat, G. Rote, and C. Wenk. Matching planar maps. J. Algorithms, 49(2):262– 283, Nov 2003.
- H. Alt and M. Godau. Computing the Fréchet distance between two polygonal curves. International Journal of Computational Geometry and Applications, 5:75–91, 1995.
- G. K. Das, R. Fraser, A. Lòpez-Ortiz, and B. G. Nickerson. On the discrete unit disk cover problem. In *Proc. of the 5th Int. Conf. on WALCOM: algorithms and computation*, WAL-COM'11, pages 146–157, Berlin, Heidelberg, 2011. Springer-Verlag.
- T. Eiter and H. Mannila. Computing discrete Fréchet distance. Technical Report CD-TR 94/64, Information Systems Department, Technical University of Vienna, 1994.
- R. Fraser and A. Lòpez-Ortiz. The within-strip discrete unit disk cover problem. In Proc. of the 24th Canadian Conf. on Computational Geometry, CCCG'12, pages 53–58, 2012.
- M. Fréchet. Sur quelques points du calcul fonctionnel. Rendiconti del Circolo Matematico di Palermo (1884 - 1940), 22(1):1–72, Dec. 1906.
- 10. M. Jiang. Map Labeling with Circles. PhD thesis, Montana State University, 2005.
- D. Lichtenstein. Planar Formulae and Their Uses. SIAM Journal on Computing, 11(2):329– 343, 1982.
- A. Maheshwari, J.-R. Sack, K. Shahbaz, and H. Zarrabi-Zadeh. Staying close to a curve. In *Proc. of the 23rd Canadian Conf. on Computational Geometry*, CCCG'11, 2011. August 10-12, 2011.
- A. Mosig and M. Clausen. Approximately matching polygonal curves with respect to the Fréchet distance. *Computational Geometry: Theory and Applications*, 30(2):113–127, Feb 2005.
- 14. N. H. Mustafa and S. Ray. Improved results on geometric hitting set problems. *Discrete and Computational Geometry*, 44(4):883–895, Dec 2010.
- 15. K. Shahbaz. Applied Similarity Problems Using Fréchet Distance. PhD thesis, Carleton University, 2013.
- A. Wolff. A simple proof for the NP-hardness of edge labeling. Technical Report W-SPNPH-00, Institut für Mathematik und Informatik, Universität Greifswald, 2000.
- 17. T. Wylie. *The Discrete Fréchet Distance with Applications*. PhD thesis, Montana State University, 2013.
- T. Wylie and B. Zhu. Discretely following a curve (short abstract). In *Computational Geometry: Young Researchers Forum*, CG:YRF'12, pages 33–34, 2012.